BIG DATA ANALYTICS

SPECTRAL CLUSTERING

- Limitations of Distance Based Clustering
- Similarity Graphs: ϵ -neighborhood & (mutual) knn graphs
- Graph Partition and Cuts
- Spectral Graph Theory
- (Un)Normalized Graph Laplacians
- Relation of Graph Laplacian and Partition
- Spectral Clustering into 2 Clusters
- Spectral Clustering into k Clusters

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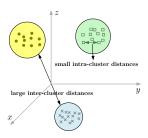
Limitations of Distance Based Clustering

Clustering: Definition

Clustering/cluster analysis/data segmentation

Grouping of objects into clusters such that objects in the same cluster are more similar and objects in different clusters are less similar

- Intra-cluster distances (between pairs of points in the same cluster)
- Inter-cluster distances (between pairs of points in different clusters)

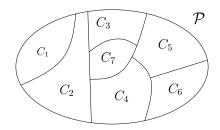


clustering hypothesis: Points in same cluster are semantically similar

Clustering: Definition

Generally, clustering produces a partition $[C_1, C_2, \ldots, C_k]$ of the dataset \mathcal{P}

- Each $C_i \subseteq \mathcal{P}$
- For $i \neq j$, $C_i \cap C_j = \emptyset$
- $\bigcup_{i=1}^k C_i = \mathcal{P}$



Clustering: Definition

Generally, clustering produces a partition $[C_1, C_2, \dots, C_k]$ of the dataset \mathcal{P}

Two broadly different ways of clustering depending on input

Input: Given a dataset (feature vectors) and a proximity measure

Output: Clusters of the dataset into *k* clusters

Alternatively,

Input: Given pairwise proximity values for a (abstractly described) dataset (e.g. distance or similarity matrix)

Output: Clusters of the dataset into *k* clusters

The number of clusters k may or may not be part of the input (fixed)

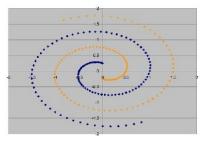
Basic Clustering Methods

- Broadly clustering methods are
 - Distance Based
 - Density and grid-based methods
 - Generative Model based
 - Other methods used for specific data types
 - e.g. for graph data we used connectivity based clustering
- It is possible that different clustering methods generate different clusterings of same data set

Distance measure does not always capture semantic clustering in the data

Limitation of distance-based clustering

Distance measure does not always capture semantic clustering in the data



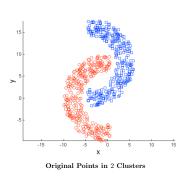
Dataset exhibits complex cluster shapes

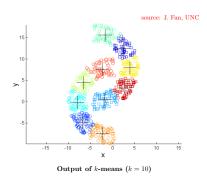
⇒ **K-means** performs very poorly in this space due bias toward dense spherical clusters.

Relationship vs. Geometry Distance

Limitation of distance-based clustering

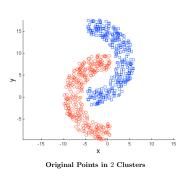
Distance measure does not always capture semantic clustering in the data

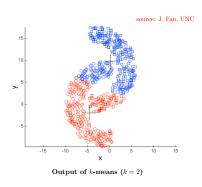




Limitation of distance-based clustering

Distance measure does not always capture semantic clustering in the data





Similarity Graphs

Similarity Graphs

Graph-based Representation of Data Relationships

Using Graphs to summarize proximity between pairs of Points

Some datasets are already Graphs – Assume adjacency capture relationships

- Web graphs
- Protein-Protein Interaction Networks
- Social Networks
- Coauthorship or Citation Networks

Similarity Graphs

Pairwise proximity is represented with graphs

Given similarity information

▷ e.g. proximity matrix of abstract objects

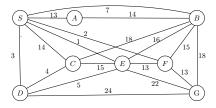
 $\mathcal{P} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$

- ⊳ Feature vectors or abstractly described
- $n \times n$ proximity matrix: $S(i,j) = sim(\mathbf{x}_i, \mathbf{x}_j)$ \triangleright Could be distance

Represent the data by a weighted graph G = (V, E)

- $V = \mathcal{P}$
- \blacksquare E: Make an edge b/w vertices with weight = pairwise similarity

	Similarity Matrix												
	S	A	В	С	D	Е	F	G					
S	∞	13	7	14	3	1	2	0					
A	13	∞	14	0	0	0	0	0					
В	7	14	∞	18	0	16	15	18					
C	14	0	18	∞	4	15	0	0					
D	3	0	0	4	∞	5	0	24					
E	1	0	16	15	5	∞	13	22					
F	2	0	15	0	0	13	∞	13					
G	0	0	18	0	24	22	13	∞					



Similarity Graph: ϵ -neighborhood Graph

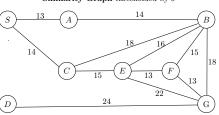
 ϵ -neighborhood graphs: points are vertices and two vertices are adjacent if there distance is at most ϵ

No need for weights, as similarities are thresholded

Simi	larity	Matrix

	S	Α	В	С	D	E	F	G
S	∞	13	7	14	3	1	2	0
Α		∞						
В	7	14	∞	18	0	16	15	18
С	14	0	18	∞	13	15	0	0
D	3	0	0	13	∞	12	0	24
Е	1	0	16	15	12	∞	13	22
F	2	0	15	0	0	13	∞	13
G	0	0	18	0	24	22	13	∞

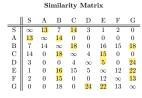
Similarity Graph thresholded by 9



 ϵ -neighborhood graphs are usually constructed from normalized distance matrix

Similarity Graph: k-NN Graph

k-NN Graph: $(v_i, v_j) \in E$ if $v_j \in k$ -NN (v_i) OR $v_i \in k$ -NN (v_j)



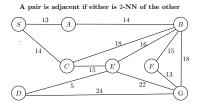
Make edge v_i to $v_i \in k$ -NN (v_i)

▷ nearest neighbors are not symmetric

Make *G* undirected by ignoring directions

▶ OR of nearest neighbors

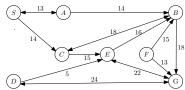
	Similarity Matrix												
	S	Α	В	С	D	Е	F	G					
S	∞	13	7	14	3	1	2	0					
A	13	∞	14	0	0	0	0	0					
В	7	14	∞	18	0	16	15	18					
C	14	0	18	∞	4	15	0	0					
D	3	0	0	4	∞	5	0	24					
E	1	0	16	15	5	∞	12	22					
F	2	0	15	0	0	12	∞	13					
G	0	0	18	0	24	22	13	∞					



Similarity Graph: Mutual k-NN Graph

Mutual k-NN Graph: $(v_i, v_j) \in E$ if $v_j \in k$ -NN (v_i) AND $v_i \in k$ -NN (v_j)

Every vertex has 2 nearest neighbors as outneighbors



Make edge v_i to $v_j \in k\text{-NN}(v_i)$

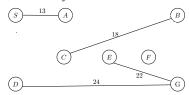
Keep only bidirectional edges

	Similarity Matrix											
	S	A	В	C	D	Е	F	G				
S	∞	13	7	14	3	1	2	0				
A	13	∞	14	0	0	0	0	0				
В	7	14	∞	18	0	16	15	18				
C	14	0	18	∞	4	15	0	0				
D	3	0	0	4	∞	5	0	24				
E	1	0	16	15	5	∞	12	22				
F	2	0	15	0	0	12	∞	13				
G	0	0	18	0	24	22	13	∞				

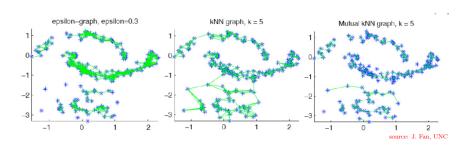
▷ nearest neighbors are not symmetric

▶ AND of nearest neighbors

Two vertices are adjacent if both are each other's 2-NN

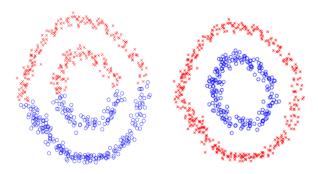


Similarity Graph: Advantages



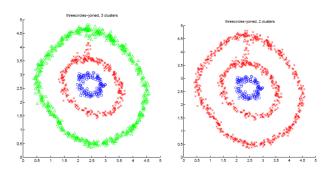
- Graphs capture local neighborhoods
- Can reliably indicate which points are "similar" or close
- Similarity values reliably encode local structure
- The similarity matrix doesn't capture global structure

Similarity Graph: Advantages



- Graphs capture local neighborhoods
- Can reliably indicate which points are "similar" or close
- Similarity values reliably encode local structure
- The similarity matrix doesn't capture global structure

Similarity Graph: Advantages



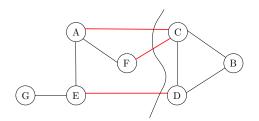
- Graphs capture local neighborhoods
- Can reliably indicate which points are "similar" or close
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- The similarity matrix doesn't capture global structure

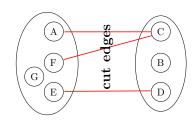
Graph Partition Using Cut

Cuts in Graphs

A cut in G is a subset $S \subset V$

- Denoted as $[S, \overline{S}]$
- $S = \emptyset$ and S = V are trivial cuts, we assume that $\emptyset \neq S \neq V$
- \blacksquare A graph on *n* vertices has 2^n cuts
- An edge (u, v) is crossing the cut $[S, \overline{S}]$, if $u \in S$ and $v \in \overline{S}$



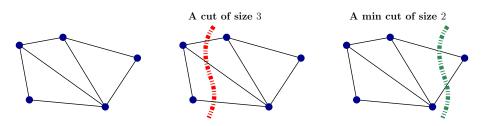


The MIN-CUT(G) problem

A cut in G is a subset $S \subset V$

- Denoted as $[S, \overline{S}]$
- An edge (u, v) is crossing the cut $[S, \overline{S}]$, if $u \in S$ and $v \in \overline{S}$

Size (or cost) of a cut in the number of crossing edges



In weighted graph size of cut is the sum of weights of crossing edges

Graph Bi-Partition Using Cut

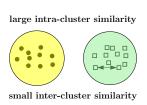
We can find a minimum-cut in the graph to separate clusters of objects

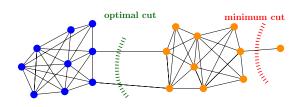
■ Partition V into $[S, \overline{S}]$, that minimizes

$$cut(S, \overline{S}) = \sum_{(u,v)\in E, u\in A, v\in \overline{S}} 1$$

Attempts to minimize inter-cluster(s) similarity but

- Does not consider maximizing intra-cluster(s) similarity
- May find trivial cut ($[\{v\}, \overline{\{v\}}]$), i.e. doesn't consider size of clusters





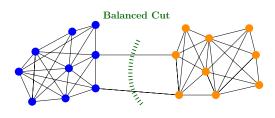
Graph BiPartition Using Balanced -Cut

To avoid trivial cuts we change the objective function of cut

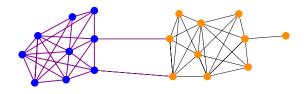
■ Partition V into $[S, \overline{S}]$, such that $|S| = |\overline{S}|$ that minimizes

$$cut(S,\overline{S}) = \sum_{(u,v)\in E, u\in A, v\in \overline{S}} \mathbf{1}$$

- lacktriangle Technically, one requires $|S| = |\overline{S}| \pm 1$
- More generally, $|S|, |\overline{S}| \ge \alpha n$



Graph BiPartition Using Ratio-Cut



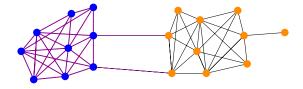
A slightly relaxed way for good and balanced cut is to minimize Ratio-Cut

■ Partition V into $[S, \overline{S}]$ that minimizes

Ratio-Cut
$$(S, \overline{S}) := \frac{cut(S, \overline{S})}{|S|} + \frac{cut(S, \overline{S})}{|\overline{S}|}$$

Graph BiPartition Using Normalized-Cut

For
$$A \subset V$$
, let $vol(A) = \sum_{x \in A} deg(x)$



- Consider connectivity between groups relative to density of each group
- Partition V into $[S, \overline{S}]$, that minimizes

$$\mathsf{normalized\text{-}cut}(S,\overline{S}) \ = \ \textit{Ncut}(S,\overline{S}) := \frac{\textit{cut}(S,S)}{\textit{vol}(S)} + \frac{\textit{cut}(S,S)}{\textit{vol}(\overline{S})}$$

- Consider both inter-cluster(s) and intra-cluster similarity
- Generally produces more balanced partitions

Graph Partition Using Cut

Finding minimum cut is easy (recall max-flow-min-cut theorem and Karger-Stein Algo)

Finding optimal balanced, ratio and normalized-cut are $\operatorname{NP-HARD}$

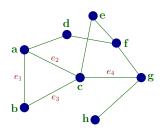
Spectral Graph Theory

Spectral Graph theory

- Spectral graph theory is using techniques from linear algebra to solve graph theory problems
- Particularly, what combinatorial properties of the graphs are implied by the eigenvalues and eigenvectors of the matrices associated with graphs

Adjacency Matrix of Graphs

Adjacency Matrix



A is symmetric and real \implies all eigenvectors are real and orthogonal

Let $\mathbf{x} \in \mathbb{R}^n$

▷ coordinates corresponding to vertices (fixed order)

Meaning of Ax = y?

 \triangleright \mathbf{y}_i is sum of \mathbf{x}_j of all neighbors of $v_i \in V$

Adjacency Matrix of Graphs

Adjacency Matrix

Suppose *G* is a *d*-regular connected graph

▷ every vertex has degree d

Let
$$\mathbf{x} = \begin{bmatrix} 1, 1, \dots, 1 \end{bmatrix}^T$$

$$Ax = dx$$

 \mathbf{x} is an eigenvector of A with eigenvalue d

Adjacency Matrix of Graphs

Adjacency Matrix

Suppose G is d-regular with 2 components $\{v_1,\ldots,v_k\}$, $\{v_{k+1},\ldots,v_n\}$

Let
$$\mathbf{x_1} = \left[\underbrace{1, 1, \dots, 1}_{k}, \underbrace{0, 0, \dots, 0}_{n-k}\right]^{T}$$

$$A\mathbf{x_1} = d\mathbf{x_1}$$

Let
$$\mathbf{x_s} = \left[\underbrace{0,0,\ldots,0}_{k},\underbrace{1,1,\ldots,1}_{n-k}\right]^T$$

$$A\mathbf{x_2} = d\mathbf{x_2}$$

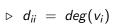
 x_1 and x_2 are eigenvectors of A with eigenvalues d

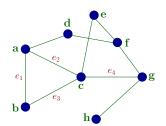
Degree Matrix of Graphs

Degree Matrix

D is an $n \times n$ diagonal matrix

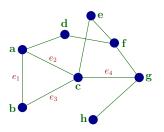
$$D = [d_{ii}]$$





Laplacian Matrix, L = D - A

$$L(i,j) = \begin{cases} d_i & \text{if } i = j \\ -1 & \text{if } i \sim j \\ 0 & \text{else} \end{cases}$$



							f		
L =	a	3 -1 -1 -1 0 0 0 0 0	-1	-1	-1	0	0	0	0
	Ь	-1	2	-1	0	0	0	0	0
	С	-1	-1	4	0	-1	0	-1	0
	d	-1	0	0	2	0	-1	0	0
	e	0	0	-1	0	2	-1	0	0
	f	0	0	0	-1	-1	3	-1	0
	g	0	0	-1	0	0	-1	3	-1
	h	0	0	0	0	0	0	-1	1

Laplacian Matrix, L = D - A

$$L(i,j) = \begin{cases} d_i & \text{if } i = j \\ -1 & \text{if } i \sim j \\ 0 & \text{else} \end{cases}$$

Let
$$\mathbf{x} = \begin{bmatrix} 1, 1 \dots, 1 \end{bmatrix}^T$$

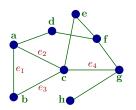
$$Lx = 0 = 0x$$

x is a (trivial) eigenvector

Laplacian Matrix, L = D - A

For $e = (u, v) \in E$, define matrix L_e as

$$L_{e}(i,j) = \begin{cases} 1 & \text{if } i = j \& i \in \{u,v\} \\ -1 & \text{if } (i,j) = (u,v) \text{ or } (i,j) = (v,u) \\ 0 & \text{else} \end{cases}$$



L_{e_1}	a	b		d	e	f	g	h
a	1	-1	0	0	0	0	0	0
b	-1	1	0	0	0	0	0	0
c	1 -1 0 0 0 0	0	0	0	0	0	0	0
d	0	0	0	0	0	0	0	0
e	0	0	0	0	0	0	0	0
f	0	0	0	0	0	0	0	0
g	0	0	0	0	0	0	0	0
1		0	0	0	0	0	0	0

	L_{e_4}	a	b	$^{\rm c}$	d	e	f	g	h
ĺ	a	0	0	0	0	0	0	0	0
	b	0	0	0	0	0	0	0	0
	c	0	0	1	0	0	0	-1	0
	d	0	0	0	0	0	0	0	0
	e	0	0	0	0	0	0	0	0
	f	0	0	0	0	0	0	0	0
	g	0	0	-1	0	0	0	1	0
	h	0	0	0	0	0	0	0	0

Laplacian Matrix, L = D - A

$$L(i,j) = \begin{cases} d_i & \text{if } i = j \\ -1 & \text{if } i \sim j \\ 0 & \text{else} \end{cases}$$

For $e = (u, v) \in E$, matrix L_e

$$L_{e}(i,j) = \begin{cases} 1 & \text{if } i = j \& i \in \{u,v\} \\ -1 & \text{if } (i,j) = (u,v) \text{ or } (i,j) = (v,u) \\ 0 & \text{else} \end{cases}$$

 L_e is actually contribution of e = (u, v) to L. So

$$L = \sum_{e \in E} L_e$$

Graph Laplacian

For edge
$$e = (u, v)$$
 $L_e(i, j) = \begin{cases} 1 & \text{if } i = j \& i \in \{u, v\} \\ -1 & \text{if } (i, j) = (u, v) \text{ or } (i, j) = (v, u) \\ 0 & \text{else} \end{cases}$

Graph Laplacian,
$$L = D - A = \sum_{e \in E} L_e$$

For any vector
$$\mathbf{x} \in \mathbb{R}^n$$
, $\mathbf{x}^T L_e \mathbf{x} = (x_i - x_j)^2$

$$\mathbf{x}^{T} L \mathbf{x} = \mathbf{x}^{T} (L_{e_1} + L_{e_2} + \ldots + L_{e_s}) \mathbf{x} = \mathbf{x}^{T} \sum_{(i,j) \in E} L_{(i,j)} \mathbf{x}$$
$$= \sum_{(i,j) \in E} (\mathbf{x}^{T} L_{(i,j)} \mathbf{x}) = \sum_{(i,j) \in E} (x_i - x_j)^2$$

Relation of Graph Laplacian with Balanced Bi-partition

Graph Laplacian, L = D - A

For any vector
$$\mathbf{x} \in \mathbb{R}^n$$
, $\mathbf{x}^T L \mathbf{x} = \sum_{(i,j) \in E} (x_i - x_j)^2$

The optimization problem of balanced bipartition

Assign labels to vertices
$$x_i = \begin{cases} 1 & \text{if } i \in S \\ -1 & \text{if } i \in \overline{S} \end{cases}$$

Find $\mathbf{x} \in \{-1, 1\}^n$ such that

$$\sum_{(i,j)\in E} (x_i - x_j)^2 \text{ is minimum}$$

b few cut edges
 b few cut edges
 contact edges

$$\sum_{x_i=-1} = \sum_{x_i=1} \implies \sum_i x_i = 0$$

▷ Balanced parts

Graph Laplacian

Graph Laplacian, L = D - A

- *L* is real & symmetric
- For any $\mathbf{x} \in R^n$ $\mathbf{x}^T L \mathbf{x} = \sum_{(i,j) \in E} (x_i x_j)^2$
- *L* is positive semidefinite $\forall \mathbf{x} \in \mathbb{R}^n, \ \mathbf{x} \neq \mathbf{0} \ \mathbf{x}^T L \mathbf{x} \geq 0$

Theorem (Spectral Theorem)

If M is a real, symmetric and positive semidefinite $n \times n$ matrix, then M has n real, non-negative, orthonormal eigen values and eigen vectors

By Spectral Theorem, L has n real eigen values $\lambda_1, \ldots, \lambda_n$

$$0 \le \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$$

Graph Laplacian and Graph Components

Find $\mathbf{x} \in \{-1,1\}^n$ such that

 $\sum_{(i,j)\in E} (x_i - x_j)^2 \text{ is minimum}$

⊳ few cut edges

 $\sum_{x_i=-1} = \sum_{x_i=1} \implies \sum_i x_i = 0$

▷ Balanced

Since
$$\mathbf{x}^T L \mathbf{x} = \sum_{(i,j) \in E} (x_i - x_j)^2$$
, minimizing $\mathbf{x}^T L \mathbf{x}$ is a continuous relaxation of the discrete optimization problem

In the following we first see connections between graph connectivity and eigenvalues/vectors of L, which provides the basis of spectral clustering

For any
$$\mathbf{x} \in \mathbb{R}^n$$
, $\mathbf{x}^T L \mathbf{x} = \sum_{(i,j) \in E} (x_i - x_j)^2$
$$0 \le \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$$

If
$$\lambda \mathbf{x} = L\mathbf{x}$$
, then $\lambda = \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$

$$\lambda_1 = 0$$
, consider $\mathbf{x} = \begin{bmatrix} 1, 1, \dots, 1 \end{bmatrix}^T \in \mathbb{R}^n$

$$\mathbf{x}^T L \mathbf{x} = \sum_{(i,j) \in E} (x_i - x_j)^2 = 0$$

or
$$L \, {f 1} = 0 \cdot {f 1}$$

Thus $\lambda_1=0$ for any \emph{L} , and $\emph{\textbf{x}}_1=\begin{bmatrix}1,1,\ldots,1\end{bmatrix}^{\emph{T}}$ is the eigenvector

Let L be the Laplacian of a graph G = (V, E), |V| = n

$$0 \le \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$$

If
$$\lambda \mathbf{x} = L\mathbf{x}$$
, then $\lambda = \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$

$$\lambda_1 = \min_{\mathbf{x} \neq 0} \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$
 (say $\mathbf{x_1}$ is a solution)

$$\lambda_2 = \min_{\mathbf{x} \neq 0, \mathbf{x} \perp \mathbf{x}_1} \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$
 (say \mathbf{x}_2 is a solution)

$$\lambda_3 = \min_{\mathbf{x} \neq 0, \mathbf{x} \perp \mathbf{x}_1, \mathbf{x}_2} \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$
 (yield \mathbf{x}_3 and so on)

Let L be the Laplacian of a graph G=(V,E) , |V|=n

$$0 \le \lambda_1 \le \lambda_2 \le \ldots \le \lambda_n$$

Theorem

 $\lambda_1=0$, and $\mathbf{x_1}=\begin{bmatrix}1,1,\ldots,1\end{bmatrix}^T\in\mathbb{R}^n$ is the corresponding eigenvector

Observe it for a few graphs, at least the following

Theorem

If G is connected, then $\lambda_2 > 0$

$$\mathbf{x_1} = \begin{bmatrix} 1, \dots, 1 \end{bmatrix}^T$$
, $\mathbf{x} \perp \mathbf{x_1} \implies \mathbf{x}^T \mathbf{1} = 0 \implies \sum_{i=1}^n x_i = 0$

$$\lambda_2 = \min_{\mathbf{x} \neq 0, \mathbf{x} \perp \mathbf{x}_1} \frac{\mathbf{x}^T \mathbf{L} \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \implies \lambda_2 = \min_{\mathbf{x} \neq \mathbf{0}, \sum_{i=1}^n x_i = 0} \frac{\mathbf{x}^T \mathbf{L} \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$

$$\lambda_2 = \min_{\substack{x \neq 0, \sum_{i=1}^{n} x_i = 0}} \sum_{(i,j) \in E} (x_i - x_j)^2$$

$$\mathbf{x_2} = argmin_{\mathbf{x} \neq \mathbf{0}, \sum\limits_{i=1}^{n} x_i = 0} \sum_{(i,j) \in E} (x_i - x_j)^2$$

Theorem

If G is connected, then $\lambda_2 > 0$

$$\lambda_2 = 0 \implies \min_{\mathbf{x} \neq \mathbf{0}, \sum_{i=1}^{n} x_i = 0} \sum_{(i,j) \in E} (x_i - x_j)^2 = 0$$

- for all edges $(u, v) \in E$ we have $x_u = x_v$
- x_i's must be equal across any path
- G is connected, there is a path b/w all u and v
- \mathbf{x}_i should be equal for all vertices
- $\mathbf{x} = \alpha \cdot [1, 1, \dots, 1]^T$
- lacksquare x is not orthogonal to x_1 , or x=0

Theorem

If G is connected \quad if and only if $\quad \lambda_2 > 0$

$$\lambda_2 = 0 \implies \min_{\mathbf{x} \neq \mathbf{0}, \sum_{i=1}^n x_i = 0} \sum_{(i,j) \in E} (x_i - x_j)^2 = 0$$

Suppose G has two components, S, \overline{S} , then

$$\mathbf{x_1} = \left[\underbrace{1,1,\ldots,1}_{i \in S},\underbrace{0,0,\ldots,0}_{i \in \overline{S}}\right]^T$$
 and $\mathbf{x_2} = \left[\underbrace{0,0,\ldots,0}_{i \in S},\underbrace{1,1,\ldots,1}_{i \in \overline{S}}\right]^T$

are clearly eigen vectors with eigen values 0

This very easy to verify by reasoning very similar to the above

Theorem

If G is connected if and only if $\lambda_2 > 0$

Theorem

The multiplicity k of the 0 eigen values of L(G) is equal to the number of connected components of G

This can be proved with the same reasoning as above

We want to see how robust these results are.

If $\lambda_2 = 0$, graph has 2 components

If $\lambda_2 = 0.00001$, graph has 2 sparsely connected parts

Theorem

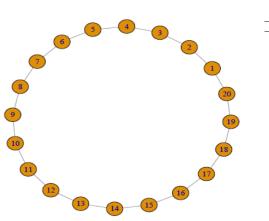
The multiplicity k of the 0 eigen values of L(G) is equal to the number of connected components of G

We want to see how robust these results are.

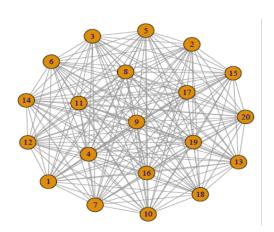
If $\lambda_2 = 0$, graph has 2 components

If $\lambda_2 = 0.00001$, graph has 2 sparsely connected parts

Lets observe the above theorem with the few examples



λ_1	λ_2	λ_3
1.78E-15	9.79E-02	9.79E-02
$\mathbf{x_1}$	$\mathbf{x_2}$	x_3
-0.2236068	0.3162278	0
-0.2236068	0.3007505	0.09771975
-0.2236068	0.2558336	0.185874
-0.2236068	0.185874	0.2558336
-0.2236068	0.09771975	0.3007505
-0.2236068	1.143599E-14	0.3162278
-0.2236068	-0.09771975	0.3007505
-0.2236068	-0.185874	0.2558336
-0.2236068	-0.2558336	0.185874
-0.2236068	-0.3007505	0.09771975
-0.2236068	-0.3162278	4.664828E-16
-0.2236068	-0.3007505	-0.09771975
-0.2236068	-0.2558336	-0.185874
-0.2236068	-0.185874	-0.2558336
-0.2236068	-0.09771975	-0.3007505
-0.2236068	1.104329E-14	-0.3162278
-0.2236068	0.09771975	-0.3007505
-0.2236068	0.185874	-0.2558336
-0.2236068	0.2558336	-0.185874
-0.2236068	0.3007505	-0.09771975



7.1	7.12	
0	20	
\mathbf{x}_1	x ₂	$\mathbf{x_3}$
-0.2236068	-0.020559652	0
-0.2236068	0.108807659	0.04
-0.2236068	-0.803711507	0.01
-0.2236068	-0.191901761	-0.1
-0.2236068	-0.222135891	0.06
-0.2236068	-0.123007583	-0.1
-0.2236068	-0.084541146	0.45
-0.2236068	-0.041279066	0.10
-0.2236068	0.006026719	-0.3
-0.2236068	0.006026719	0.23
-0.2236068	0.045614464	0.02
-0.2236068	0.045614464	-0.5
-0.2236068	0.102436277	-0.2
-0.2236068	0.095619485	0.11
-0.2236068	0.095619485	0.11
-0.2236068	0.132014323	0.12
-0.2236068	0.201951467	0.27
-0.2236068	0.201951467	0.05
-0.2236068	0.208431342	-0.0

λ_1	λ_2	λ_3
0	20	20
x ₁		x ₃
-0.2236068	-0.020559652	0
-0.2236068	0.108807659	0.04273661
-0.2236068	-0.803711507	0.0115485
-0.2236068	-0.191901761	-0.10229988
-0.2236068	-0.222135891	0.06658875
-0.2236068	-0.123007583	-0.15801353
-0.2236068	-0.084541146	0.45265136
-0.2236068	-0.041279066	0.10869576
-0.2236068	0.006026719	-0.39124179
-0.2236068	0.006026719	0.23205375
-0.2236068	0.045614464	0.02944336
-0.2236068	0.045614464	-0.56047404
-0.2236068	0.102436277	-0.29818941
-0.2236068	0.095619485	0.1104163
-0.2236068	0.095619485	0.1104163
-0.2236068	0.132014323	0.1210102
-0.2236068	0.201951467	0.27869041
-0.2236068	0.201951467	0.05981768
-0.2236068	0.208431342	-0.01290196
-0.2236068	0.237022732	-0.10094836





-3.55E-15	-3.55E-15	1.00E+01
$\mathbf{x_1}$	$\overline{\mathbf{x_2}}$	$\mathbf{x_3}$
-0.3162278	0	0
-0.3162278	0	-0.07607884
-0.3162278	0	0.08239587
-0.3162278	0	0.10999263
-0.3162278	0	0.23285916
-0.3162278	0	0.42651362
-0.3162278	0	0.1775714
-0.3162278	0	-0.83645416
-0.3162278	0	-0.0826799
-0.3162278	0	-0.03411978
0	-0.3162278	0
0	-0.3162278	0
0	-0.3162278	0
0	-0.3162278	0
0	-0.3162278	0
0	-0.3162278	0

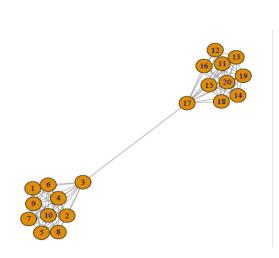
-0.3162278 -0.3162278 -0.3162278 -0.3162278

0

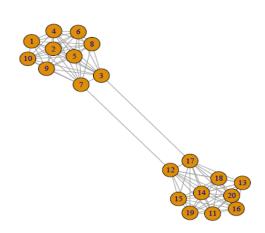
 λ_2

 λ_3

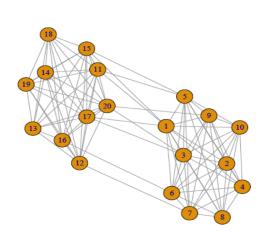
 λ_1



λ_1	λ_2	λ_3
1.24E-14	1.69E-01	1.00E+01
<u>x</u> 1		
0.2236068	-0.2271498	0
0.2236068	-0.2271498	-0.187336735
0.2236068	-0.1887505	0.180331703
0.2236068	-0.2271498	0.026000794
0.2236068	-0.2271498	0.240657356
0.2236068	-0.2271498	-0.081758805
0.2236068	-0.2271498	0.109554976
0.2236068	-0.2271498	0.481534166
0.2236068	-0.2271498	-0.764973527
0.2236068	-0.2271498	-0.004009928
0.2236068	0.2271498	-0.047287728
0.2236068	0.2271498	-0.014797013
0.2236068	0.2271498	-0.042955103
0.2236068	0.2271498	-0.004581612
0.2236068	0.2271498	-0.008986301
0.2236068	0.2271498	-0.004581612
0.2236068	0.1887505	0.180331703
0.2236068	0.2271498	-0.019047445
0.2236068	0.2271498	-0.019047445
0.2236068	0.2271498	-0.019047445



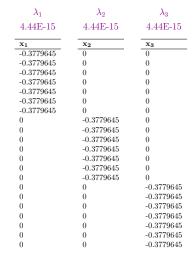
λ_1	λ_2	λ_3
-1.78E-15	3.43E-01	1.00E+01
$\mathbf{x_1}$		x ₃
0.2236068	-0.2309699	0
0.2236068	-0.2309699	-0.257554654
0.2236068	-0.1913417	0.417497079
0.2236068	-0.2309699	-0.196918966
0.2236068	-0.2309699	0.229066071
0.2236068	-0.2309699	0.339796713
0.2236068	-0.1913417	-0.207932922
0.2236068	-0.2309699	0.252674051
0.2236068	-0.2309699	-0.450305694
0.2236068	-0.2309699	-0.126321678
0.2236068	0.2309699	-0.052770238
0.2236068	0.1913417	-0.207932922
0.2236068	0.2309699	-0.029543845
0.2236068	0.2309699	-0.010168603
0.2236068	0.2309699	-0.005308371
0.2236068	0.2309699	-0.005308371
0.2236068	0.1913417	0.417497079
0.2236068	0.2309699	-0.052770238
0.2236068	0.2309699	-0.001792058
0.2236068	0.2309699	-0.051902431



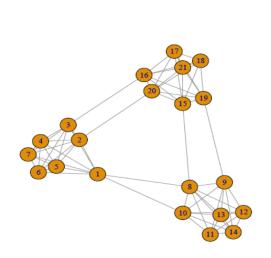
λ_1	λ_2	λ_3
1.42E-14	1.66E+00	1.00E+01
x ₁		x ₃
-0.2236068	-0.1460852	-0.08215129
-0.2236068	-0.2639678	-0.1809219
-0.2236068	-0.1784494	-0.08215129
-0.2236068	-0.2639678	-0.16323835
-0.2236068	-0.1777733	-0.08215129
-0.2236068	-0.2129005	-0.19414333
-0.2236068	-0.2129005	0.4683991
-0.2236068	-0.2639678	0.5743843
-0.2236068	-0.2169969	-0.08215129
-0.2236068	-0.2639678	-0.17587465
-0.2236068	0.1815737	-0.08215129
-0.2236068	0.2129005	0.4683991
-0.2236068	0.2639678	0.10115772
-0.2236068	0.2639678	-0.03308852
-0.2236068	0.1815737	-0.08215129
-0.2236068	0.2129005	-0.19414333
-0.2236068	0.1815083	-0.08215129
-0.2236068	0.2639678	0.0026285
-0.2236068	0.2639678	-0.01634829
-0.2236068	0.174649	-0.08215129











λ_1	λ_2	λ_3
1.78E-15	6.39E-01	7.34E-01
	x	x ₃
-0.2182179	-0.12384629	-0.20165418
-0.2182179	-0.2208987	-0.17027215
-0.2182179	-0.2208987	-0.17027215
-0.2182179	-0.2395617	-0.23928643
-0.2182179	-0.2395617	-0.23928643
-0.2182179	-0.2395617	-0.23928643
-0.2182179	-0.2395617	-0.23928643
-0.2182179	0.22602667	-0.06051003
-0.2182179	0.27444989	-0.0407094
-0.2182179	0.2623651	-0.10699853
-0.2182179	0.32307908	-0.09189205
-0.2182179	0.32307908	-0.09189205
-0.2182179	0.32307908	-0.09189205
-0.2182179	0.32307908	-0.09189205
-0.2182179	-0.0414664	0.27727069
-0.2182179	-0.10218038	0.26216421
-0.2182179	-0.08351738	0.33117848
-0.2182179	-0.08351738	0.33117848
-0.2182179	-0.03488819	0.27999583
-0.2182179	-0.10218038	0.26216421

-0.08351738

-0.2182179

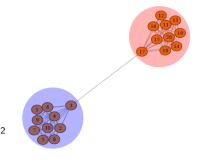
0.33117848

Spectral Clustering

Spectral Clustering

Three Steps in Spectral Bi-Partition

- Pre-processing
 - Build Graph Data Representation
 - Compute the Graph Laplacian, L
- 2 Decomposition
 - Find eigenpair $(\lambda_2, \mathbf{x_2})$ of L
 - Map vertices to coordinates of x₂
 - x₂ is 1d representation of vertices
- Grouping
 - Split vertices based on values in x₂
 - e.g. split by positive/negative, or
 - split at mean or median or
 - split by k-means on this 1d data

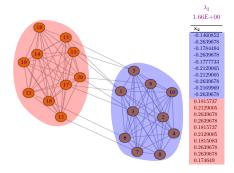


 λ_2 1.69E-01 x_2 -0.2271498
-0.2271498
-0.287505
-0.287505
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
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-0.2271498
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-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498
-0.2271498

Spectral Clustering into 2 clusters

Three Steps in Spectral Bi-Partition

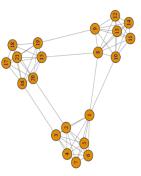
- Pre-processing
 - Build Graph Data Representation
 - Compute the Graph Laplacian, L
- 2 Decomposition
 - Find eigenpair $(\lambda_2, \mathbf{x_2})$ of L
 - Map vertices to coordinates of x₂
 - \mathbf{x}_2 is 1d representation of vertices
- 3 Grouping
 - Split vertices based on values in x₂
 - e.g. split by positive/negative, or
 - split at mean or median or
 - split by k-means on this 1d data



Spectral Clustering into k clusters

Three Steps in Spectral Partitioning into k clusters

- Pre-processing
 - Build Graph Data Representation
 - Compute the Graph Laplacian, L
- 2 Decomposition
 - Find k eigenvectors $x_1, x_2, ..., x_k$ of L
 - Map v_i to $[\mathbf{x_1}(i)\mathbf{x_2}(i)...\mathbf{x_k}(i)]$
 - $[\mathbf{x_2}(i) \dots \mathbf{x_k}(i)]$ is kd representation of v_i
- 3 Grouping
 - Cluster the vectors in \mathbb{R}^k
 - e.g. using k-means algorithm



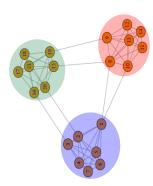
$\mathbf{x_2}$	x_3
-0.12384629	-0.20165418
-0.2208987	-0.17027215
-0.2208987	-0.17027215
-0.2395617	-0.23928643
-0.2395617	-0.23928643
-0.2395617	-0.23928643
-0.2395617	-0.23928643
0.22602667	-0.06051003
0.27444989	-0.0407094
0.2623651	-0.10699853
0.32307908	-0.09189205
0.32307908	-0.09189205
0.32307908	-0.09189205
0.32307908	-0.09189205
-0.0414664	0.27727069
-0.10218038	0.26216421
-0.08351738	0.33117848
-0.08351738	0.33117848
-0.03488819	0.27999583
-0.10218038	0.26216421
-0.08351738	0.33117848

6.39E-01

Spectral Clustering into k clusters

Three Steps in Spectral Partitioning into k clusters

- Pre-processing
 - Build Graph Data Representation
 - Compute the Graph Laplacian, L
- 2 Decomposition
 - Find k eigenvectors x_1, x_2, \dots, x_k of L
 - Map v_i to $[\mathbf{x_1}(i)\mathbf{x_2}(i)...\mathbf{x_k}(i)]$
 - $[\mathbf{x_2}(i) \dots \mathbf{x_k}(i)]$ is kd representation of v_i
- 3 Grouping
 - Cluster the vectors in \mathbb{R}^k
 - e.g. using k-means algorithm

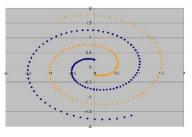


\mathbf{x}_2	x_3
-0.12384629	-0.20165418
-0.2208987	-0.17027215
-0.2208987	-0.17027215
-0.2395617	-0.23928643
-0.2395617	-0.23928643
-0.2395617	-0.23928643
-0.2395617	-0.23928643
0.22602667	-0.06051003
0.27444989	-0.0407094
0.2623651	-0.10699853
0.32307908	-0.09189205
0.32307908	-0.09189205
0.32307908	-0.09189205
0.32307908	-0.09189205
-0.0414664	0.27727069
-0.10218038	0.26216421
-0.08351738	0.33117848
-0.08351738	0.33117848
-0.03488819	0.27999583
-0.10218038	0.26216421
-0.08351738	0.33117848

6.39E-01

7.34E-0

Naive Spectral Clustering



Dataset exhibits complex cluster shapes

⇒ K-means performs very poorly in this space due bias toward dense spherical clusters.

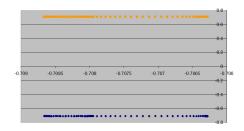
Relationship vs. Geometry Distance

source: J. Fan, UNC

source: J. Fan. UNC



In the embedded space given by two leading eigenvectors, clusters are trivial to separate.



We saw that spectral properties of Laplacian ${\it L}={\it D}-{\it A}$ coincides with Ratio-Cut objectives

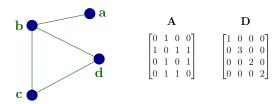
We define a Laplacian with similar spectral properties as L and coinciding with the Normalized-Cut

Symmetric Normalized Laplacian

$$L_{sym} = D^{-1/2}LD^{-1/2} = \mathbb{I} - D^{-1/2}AD^{-1/2}$$

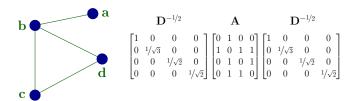
Symmetric Normalized Laplacian

$$L_{sym} = D^{-1/2}LD^{-1/2} = \mathbb{I} - D^{-1/2}AD^{-1/2}$$



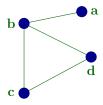
Symmetric Normalized Laplacian

$$L_{sym} = D^{-1/2}LD^{-1/2} = \mathbb{I} - D^{-1/2}AD^{-1/2}$$



Symmetric Normalized Laplacian

$$L_{sym} = D^{-1/2}LD^{-1/2} = \mathbb{I} - D^{-1/2}AD^{-1/2}$$



$$\begin{split} \mathbf{L_{sym}} &= \mathbb{I} - \mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2} \\ &\begin{bmatrix} 1 & -1/\sqrt{3} & 0 & 0 \\ -1/\sqrt{3} & 1 & -1/\sqrt{6} & -1/\sqrt{6} \\ 0 & -1/\sqrt{6} & 1 & -1/2 \\ 0 & -1/\sqrt{6} & -1/2 & 1 \end{bmatrix} \end{split}$$

The Algorithm based on Unnormalized Laplaian is due to Shi and Malick

The algorithm based on normalized Laplacian is due to Ng, Jordan, and Weiss

All spectral algorithms work for weighted graphs too, with weighted degree of a vertex defined as sum of weights of all edges incident on it