## Algorithms

## Polynomial Time Reduction

■ Polynomial Time Reduction Definition

- Reduction by Equivalence

■ Reduction from Special Cases to General Case

- Reduction by Encoding with Gadgets
- Transitivity of Reductions

■ Decision, Search and Optimization Problem

- Self-Reducibility

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## Polynomial Time Reduction

## Problem $A$ is polynomial time reducible to Problem $B$,

If any instance of problem $A$ can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem $B$

If any algorithm for problem $B$ can be used [called (once or more) with 'clever' legal inputs] to solve any instance of problem $A$

Subroutine for $B$ takes an instance $y$ of $B$ and returns the solution $B(y)$


Algorithm for $A$ transforms an instance $x$ of $A$ to an instance $y$ of $B$. Then transforms $B(y)$ to $A(x)$

## Reduction by encoding with gadgets

$$
\operatorname{SAT}(f) \leq_{p} 3-\operatorname{SAT}\left(f^{\prime}\right)
$$

Given a CNF formula $f$ on variables $X=\left\{x_{1}, \ldots, x_{n}\right\}$
Construct an equivalent 3-CNF formula $f^{\prime}$ on variables $X \cup\left\{d_{1}, d_{2}, \ldots\right\}$
■ Initialize $f^{\prime}=f$. For a long clause $C=\left(x_{i 1} \vee x_{i 2} \vee x_{i 3} \vee x_{i 4} \vee \ldots\right)$ in $f^{\prime}$

- Add the clauses $\left(x_{i 1} \vee x_{i 2} \vee d_{i}\right) \wedge\left(\bar{d}_{i} \vee x_{i 3} \vee x_{i 4} \vee \ldots\right)$ to $f^{\prime}$
- The new (long clause) is shorter than $C$

$$
(x_{i 1} \vee x_{i 2} \vee \underbrace{x_{i 3} \vee x_{i 4} \vee \cdots}_{y}) \Longleftrightarrow\left(x_{i 1} \vee x_{i 2} \vee d_{i}\right) \wedge(\bar{d}_{i} \vee \underbrace{x_{i 3} \vee x_{i 4} \vee \cdots}_{y})
$$

Proof: Suppose ( $x_{i 1} \vee x_{i 2} \vee \underbrace{x_{i 3} \vee x_{i 4} \vee \ldots}_{y}$ ) is satisfiable

- If $x_{i 1} \vee x_{i 2}=1$. Set $d_{i}=0$
- If $x_{i 1} \vee x_{i 2}=0$, then $y=1$. Set $d_{i}=1$
$\triangleright$ RHS is also satisfiable
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■ Add the clauses $\left(x_{i 1} \vee x_{i 2} \vee d_{i}\right) \wedge\left(\overline{d_{i}} \vee x_{i 3} \vee x_{i 4} \vee \ldots\right)$ to $f^{\prime}$

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$$

Proof: Suppose $\left(x_{i 1} \vee x_{i 2} \vee d_{i}\right) \wedge(\overline{d_{i}} \vee \underbrace{x_{i 3} \vee x_{i 4} \vee \ldots}_{y})$ is satisfiable

- If $d_{i}=1$, then $\overline{d_{i}}=0$ and $y=1$
- If $d_{i}=0$, then $\overline{d_{i}}=1$ and $x_{i 1} \vee x_{i 2}=1$
$\triangleright$ LHS is also satisfiable
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## Reduction by encoding with gadgets

$$
\operatorname{HAM}-\operatorname{PATH}(G) \leq_{p} \quad \operatorname{HAM}-\operatorname{CYCLE}(G)
$$

Let $\mathcal{A}$ be an algorithm for Ham-CYCle $(G)$
Given an instance $G$ of $\operatorname{HAm}-\operatorname{Path}(G)$
Let $G^{\prime}$ be $G$ plus a dummy vertex $v^{\prime}$ adjacent to all vertices in $V(G)$

$G^{\prime}$ has a Hamiltonian cycle if and only if $G$ has a Hamiltonian path

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$G^{\prime}$ has a Hamiltonian cycle if and only if $G$ has a Hamiltonian path
1 Call $\mathcal{A}$ on $G^{\prime}$
2 If $\mathcal{A}$ outputs Yes we will output Yes and vice-versa

## Polynomial Time Reduction: Cook Reducibility

$$
\operatorname{HAM}-\operatorname{CYCLE}(G) \leq_{p} \quad \operatorname{HAM}-\operatorname{PATH}(G)
$$

Let $\mathcal{A}$ be an algorithm for $\operatorname{HAM-Path(~} G$ )
Given an instance $G=(V, E)$ of Ham-CYCLE $(G)$
For each edge $e=(u, v) \in E(G)$ make the graph $G_{e}=\left(V_{e}, E_{e}\right)$
$V_{e}=V \cup\left\{u^{\prime}, v^{\prime}\right\} \quad$ and $\quad E_{e}=E \cup\left\{\left(u, u^{\prime}\right),\left(v, v^{\prime}\right)\right\}$

$G$ has a Hamiltonian cycle if and only if some $G_{e}$ has a Hamiltonian path
1 Call $\mathcal{A}$ on each of $G_{u v}$
2 If $\mathcal{A}$ outputs Yes on any $G_{e}$, we will output Yes
3 If $\mathcal{A}$ outputs No on all $G_{e}$, we will output No

