

Polynomial Time Reduction

- Polynomial Time Reduction Definition
- Reduction by Equivalence
- Reduction from Special Cases to General Case
- Reduction by Encoding with Gadgets
- Transitivity of Reductions
- Decision, Search and Optimization Problem
- Self-Reducibility

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Hard (Intractable) Problems

Efficiently Solvable Problem

\exists an $O(n^k)$ worst case time algorithm for instances of size n , constant k

- Now we study negative results
- Characterize problems for which we don't have good news
- **Cannot say they are not efficiently solvable (just don't know yet)**
- We might need to focus on approximation or special cases

Hard (Intractable) Problem

- No known $O(n^k)$ algorithm
- Exponential time is sufficient $O(n^n)$, $O(n!)$, $O(k^n)$

We establish that **these “hard problems”** are in some sense are equivalent

Polynomial Time Reduction

To explore the class of computationally hard problems, we define a notion of comparing the hardness of two problems

Measures the relative difficulty of two problems

Problem A is polynomial time reducible to Problem B , $A \leq_p B$

If any instance of problem A can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem B

▷ B is at least as hard as problem A (w.r.t polynomial time)

Extremely important (a building block) for complexity theory

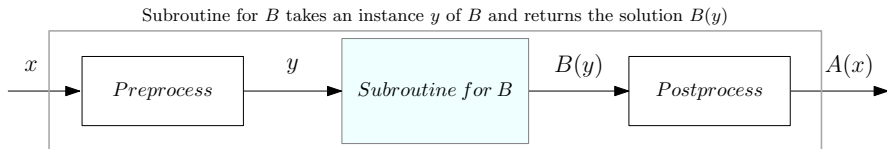
Generally confused, make sure you understand it the right way

Polynomial Time Reduction

Problem A is polynomial time reducible to Problem B , $A \leq_p B$

If any instance of problem A can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem B

If any algorithm for problem B can be used [called (once or more) with 'clever' legal inputs] to solve any instance of problem A



Algorithm for A transforms an instance x of A to an instance y of B . Then transforms $B(y)$ to $A(x)$

Polynomial Time Reduction to design algorithms

Problem A is polynomial time reducible to Problem B , $A \leq_p B$

If any instance of problem A can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem B

- $\text{FINDMIN} \leq_p \text{SORTING}$
- $\text{SORTING} \leq_p \text{FINDMIN}$
- $\text{MEDIAN} \leq_p \text{SORTING}$
- $\text{SORTING} \leq_p \text{MEDIAN}$
- $\text{CYCLE-DETECTION} \leq_p \text{DFS}$
- $\text{ALL-PAIRS-SHORTEST-PATHS} \leq_p \text{SINGLE-SOURCE-SHORTEST-PATHS}$
- $\text{SINGLE-SOURCE-SHORTEST-PATHS} \leq_p \text{ALL-PAIRS-SHORTEST-PATHS}$
- $\text{BIPARTITE-MATCHING} \leq_p \text{MAXIMUM-FLOW}$

Complete details of these (toy) reductions (calls with inputs, extra computation)