

Polynomial Time Reduction

- Polynomial Time Reduction Definition
- Reduction by Equivalence
- Reduction from Special Cases to General Case
- Reduction by Encoding with Gadgets
- Transitivity of Reductions
- Decision, Search and Optimization Problem
- Self-Reducibility

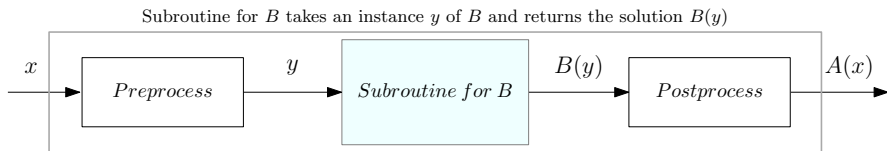
IMDAD ULLAH KHAN

Polynomial time reduction is a way to compare hardness of problems

Problem A is polynomial time reducible to Problem B , $A \leq_p B$

If any instance of problem A can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem B

If any algorithm for problem B can be used [called (once or more) with 'clever' legal inputs] to solve any instance of problem A



Algorithm for A transforms an instance x of A to an instance y of B . Then transforms $B(y)$ to $A(x)$

Reduction by encoding with gadgets

$$3\text{-SAT}(f) \leq_p \text{INDEPENDENT-SET}(G, k)$$

$$f = (x_{11} \vee x_{12} \vee x_{13}) \wedge (x_{21} \vee x_{22} \vee x_{23}) \wedge \dots \quad \dots \wedge (x_{m1} \vee x_{m2} \vee x_{m3})$$

We need to set each of x_1, \dots, x_n to 0/1 so as $f = 1$

Alternatively,

- 1 We need to pick a literal from each clause and set it to 1
- 2 But we cannot make conflicting settings

Reduction by encoding with gadgets

$$3\text{-SAT}(f) \leq_p \text{INDEPENDENT-SET}(G, k)$$

- Given f on n variables and m clauses - Make a graph G
- For each clause make a triangle with nodes labeled with literals
- For clauses with 2 and 1 literal make an edge or a node
- Make edges between literals appearing in different clauses as complements

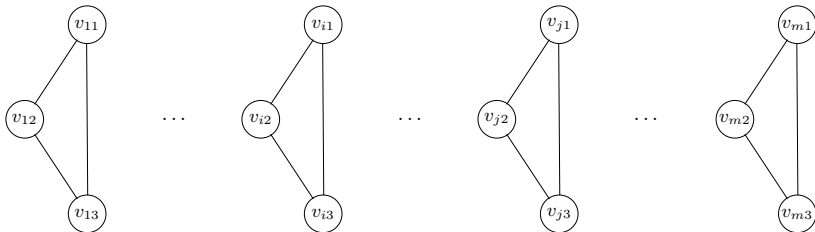
$$(x_{11} \vee x_{12} \vee x_{13}) \wedge \dots \wedge (x_{i1} \vee x_{i2} \vee x_{i3}) \wedge \dots \wedge (x_{j1} \vee x_{j2} \vee x_{j3}) \wedge \dots \wedge (x_{m1} \vee x_{m2} \vee x_{m3})$$

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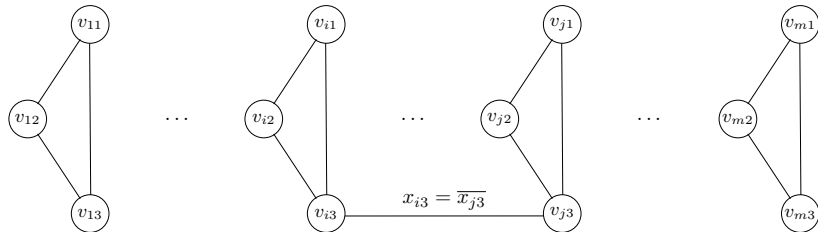


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Theorem: f is satisfiable iff G has an independent set of size m

$$(x_1 \vee x_2 \vee \overline{x_3}) \wedge (\overline{x_1} \vee \overline{x_3} \vee x_4) \wedge (\overline{x_2} \vee \overline{x_3} \vee \overline{x_4})$$

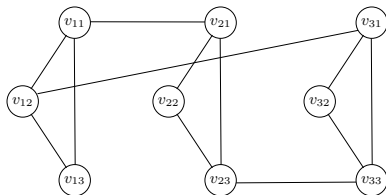
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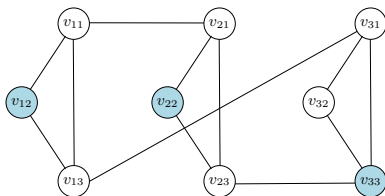
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$$x_1 = 1, \overline{x_3} = 1, \overline{x_4} = 1$$

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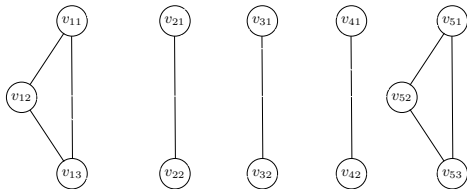
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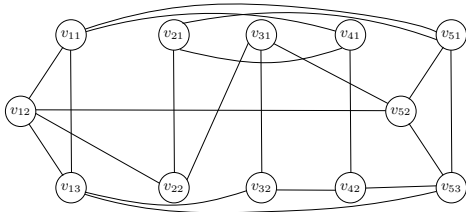
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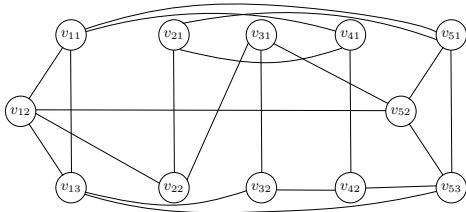
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No satisfying assignment, No independent set of size 5

Reduction by encoding with gadgets

$$3\text{-SAT}(f) \leq_p \text{INDEPENDENT-SET}(G, k)$$

Theorem: f is satisfiable iff G has an independent set of size m

The reduction is as follows:

- Let \mathcal{A} be an algorithm for the $\text{INDEPENDENT-SET}(G, k)$ problem
- We will use \mathcal{A} to solve the $3\text{-SAT}(f)$ problem
- Given any instance f of $3\text{-SAT}(f)$ on n variables and m clauses
- Construct the graph as outlined above
- Call \mathcal{A} on $[G, m]$
- if \mathcal{A} returns **Yes**, declare f satisfiable and vice-versa
- G can be constructed in time polynomial in n and m
- Hence, this is a polynomial time reduction

Reduction by encoding with gadgets

$$\text{SAT}(f) \leq_p \text{3-SAT}(f')$$

- Given a CNF formula f on variables $X = \{x_1, \dots, x_n\}$, D : new variables
- Construct an **equivalent** 3-CNF formula f' on variables $X \cup \{d_1, d_2, \dots\}$
- Initialize $f' = f$. For a long clause $C = (x_{i1} \vee x_{i2} \vee x_{i3} \vee x_{i4} \vee \dots)$ in f'
- Add the clauses $(x_{i1} \vee x_{i2} \vee d_i) \wedge (\bar{d}_i \vee x_{i3} \vee x_{i4} \vee \dots)$ to f'
- The new (long clause) is shorter than C

$$(x_{i1} \vee x_{i2} \vee \underbrace{x_{i3} \vee x_{i4} \vee \dots}_y) \iff (x_{i1} \vee x_{i2} \vee d_i) \wedge (\bar{d}_i \vee \underbrace{x_{i3} \vee x_{i4} \vee \dots}_y)$$

- Suppose $(x_{i1} \vee x_{i2} \vee \underbrace{x_{i3} \vee x_{i4} \vee \dots}_y)$ is satisfiable
- If $x_{i1} \vee x_{i2} = 1$. Set $d_i = 0$ ▷ RHS is also satisfiable
- If $x_{i1} \vee x_{i2} = 0$, then $y = 1$. Set $d_i = 1$ ▷ RHS is also satisfiable

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- If $d_i = 1$, then $\bar{d}_i = 0$ and $y = 1$ ▷ LHS is also satisfiable
- If $d_i = 0$, then $\bar{d}_i = 1$ and $x_{i1} \vee x_{i2} = 1$ ▷ LHS is also satisfiable

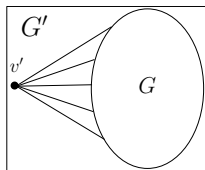
Reduction by encoding with gadgets

$$\text{HAM-PATH}(G) \leq_p \text{HAM-CYCLE}(G)$$

- Let \mathcal{A} be an algorithm for $\text{HAM-CYCLE}(G)$
- Given an instance G of $\text{HAM-PATH}(G)$
- Let G' be G plus a dummy vertex v' adjacent to all vertices in $V(G)$

G' has a Hamiltonian cycle if and only if G has a Hamiltonian path

- Call \mathcal{A} on G'
- If \mathcal{A} outputs **Yes** we will output **Yes** and vice-versa



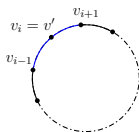
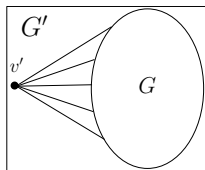
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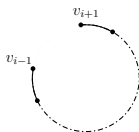
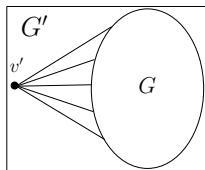
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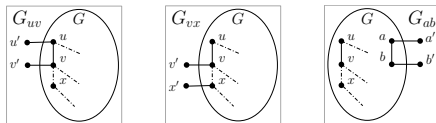
- Call \mathcal{A} on G'
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Polynomial Time Reduction: Cook Reducibility

$$\text{HAM-CYCLE}(G) \leq_p \text{HAM-PATH}(G)$$

- Let \mathcal{A} be an algorithm for $\text{HAM-PATH}(G)$
- Given an instance $G = (V, E)$ of $\text{HAM-CYCLE}(G)$
- For each edge $e = (u, v) \in E(G)$ make the graph $G_e = (V_e, E_e)$
- $V_e = V \cup \{u', v'\}$ and $E_e = E \cup \{(u, u'), (v, v')\}$



G has a Hamiltonian cycle if and only if some G_e has a Hamiltonian path

- Call \mathcal{A} on each of G_{uv} ▷ $O(|E|)$ calls
- If \mathcal{A} outputs **Yes** on any G_e , we will output **Yes**
- If \mathcal{A} outputs **No** on all G_e , we will output **No**