

## Polynomial Time Reduction

- Polynomial Time Reduction Definition
- Reduction by Equivalence
- Reduction from Special Cases to General Case
- Reduction by Encoding with Gadgets
- Transitivity of Reductions
- Decision, Search and Optimization Problem
- Self-Reducibility

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# Hard (Intractable) Problems

## Efficiently Solvable Problem

$\exists$  an  $O(n^k)$  worst case time algorithm for instances of size  $n$ , constant  $k$

Now we study negative results!

Characterize problems for which we don't have good news

Cannot say they are not efficiently solvable (just don't know yet)

## Hard (Intractable) Problem

- No known  $O(n^k)$  algorithm
- Exponential time is sufficient  $O(n^n)$ ,  $O(n!)$ ,  $O(k^n)$

We establish that these “hard problems” are in some sense are equivalent

# Polynomial Time Reduction

To explore the class of computationally hard problems, we define a notion of comparing the hardness of two problems

Measures the relative difficulty of two problems

Problem  $A$  is polynomial time reducible to Problem  $B$ ,  $A \leq_p B$

If any instance of problem  $A$  can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem  $B$

▷  $B$  is at least as hard as problem  $A$  (w.r.t polynomial time)

Extremely important (a building block) for complexity theory

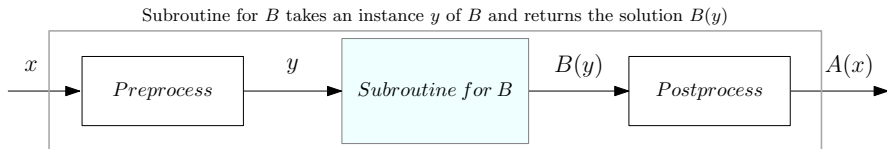
Generally confused, make sure you understand it the right way

# Polynomial Time Reduction

Problem  $A$  is polynomial time reducible to Problem  $B$ ,  $A \leq_p B$

If any instance of problem  $A$  can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem  $B$

If any algorithm for problem  $B$  can be used [called (once or more) with 'clever' legal inputs] to solve any instance of problem  $A$



Algorithm for  $A$  transforms an instance  $x$  of  $A$  to an instance  $y$  of  $B$ . Then transforms  $B(y)$  to  $A(x)$

# Polynomial Time Reduction to design algorithms

Problem  $A$  is polynomial time reducible to Problem  $B$ ,  $A \leq_p B$

If any instance of problem  $A$  can be solved using a polynomial amount of computation plus a polynomial number of calls to a solution of problem  $B$

- $\text{FINDMIN} \leq_p \text{SORTING}$
- $\text{SORTING} \leq_p \text{FINDMIN}$
- $\text{MEDIAN} \leq_p \text{SORTING}$
- $\text{SORTING} \leq_p \text{MEDIAN}$
- $\text{CYCLE-DETECTION} \leq_p \text{DFS}$
- $\text{ALL-PAIRS-SHORTEST-PATHS} \leq_p \text{SINGLE-SOURCE-SHORTEST-PATHS}$
- $\text{SINGLE-SOURCE-SHORTEST-PATHS} \leq_p \text{ALL-PAIRS-SHORTEST-PATHS}$
- $\text{BIPARTITE-MATCHING} \leq_p \text{MAXIMUM-FLOW}$

Complete details of these (toy) reductions (calls with inputs, extra computation)