

## Graphs

- Graphs are everywhere
- Types and Terminology: Handshaking lemma
- Representation, Complement, Transpose, Subgraph
- Walks, Paths and Cycles
- (Strongly) Connected and  $k$ -Connected graphs
- Applications: BFS, DFS, Eulerian graphs
- Advanced Applications: Optimization & Massive Graph Analysis

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# Graph Representation: Adjacency Matrix

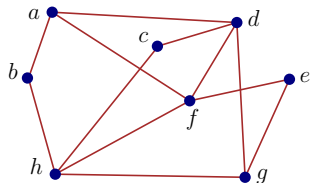
## Undirected Simple Graphs

$$G = (V, E)$$

$V$  is set of vertices

$E$  is set of edges

(unordered pairs (2-subsets) of  $V$ )



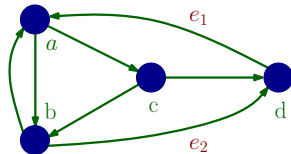
## Directed Graphs (digraphs)

$$G = (V, E)$$

$V$  is set of vertices

$E$  is set of edges

(ordered pairs of  $V$ )

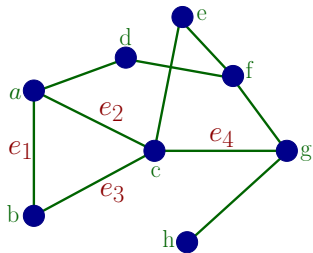


# Undirected Graph Representation: Adjacency Matrix

Represent undirected  $G = (V, E)$  with an **adjacency matrix**  $A_G$

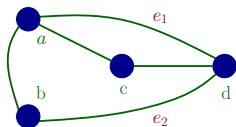
- Fix an arbitrary ordering of  $V$
- One row for each vertex in  $V$
- One column for each vertex in  $V$

$$A_{ij} = \begin{cases} 1 & \text{if } (v_i, v_j) \in E \\ 0 & \text{if } (v_i, v_j) \notin E \end{cases}$$


$$A_G =$$

	a	b	c	d	e	f	g	h
a	0	1	1	1	0	0	0	0
b	1	0	1	0	0	0	0	0
c	1	1	0	0	1	0	1	0
d	1	0	0	0	0	1	0	0
e	0	0	1	0	0	1	0	0
f	0	0	0	1	1	0	1	0
g	0	0	1	0	0	1	0	1
h	0	0	0	0	0	0	1	0

## Undirected Graph Representation: Adjacency Matrix



$$A = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$$

Let  $A$  be the adjacency matrix of a simple graph graph on  $n$  vertices.

**ICP 14-22** How many entries are there in  $A$ ?

**ICP 14-23** How many 1's are there in  $A$ ?

**ICP 14-24** How many 0's are there in  $A$ ?

**ICP 14-25** What are diagonal entries of  $A$ ?

**ICP 14-26** How many 1's are there in row corresponding to vertex  $v$ ?

**ICP 14-27** How many 1's are there in column corresponding to  $v$ ?

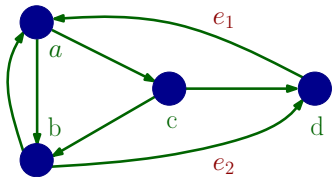
## Directed Graph Representation: Adjacency Matrix

Digraph  $G = (V, E)$  is a relation on  $V$

Represent  $G$  with an **adjacency matrix**  $A_G$

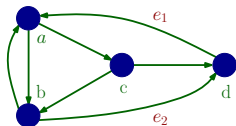
- Fix an arbitrary ordering of  $V$
- One row for each vertex in  $V$
- One column for each vertex in  $V$

$$A_{ij} = \begin{cases} 1 & \text{if } (v_i, v_j) \in E \\ 0 & \text{if } (v_i, v_j) \notin E \end{cases}$$



$$A = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

## Directed Graph Representation: Adjacency Matrix



$$A = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

Let  $A$  be the adjacency matrix of a simple digraph graph on  $n$  vertices.

**ICP 14-28** How many entries are there in  $A$ ?

**ICP 14-29** How many 1's are there in  $A$ ?

**ICP 14-30** How many 0's are there in  $A$ ?

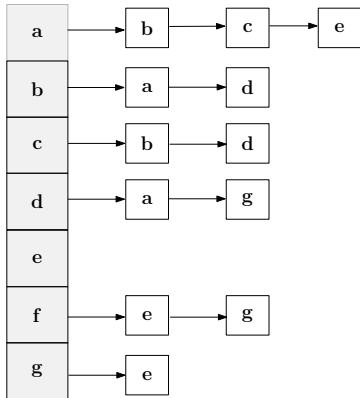
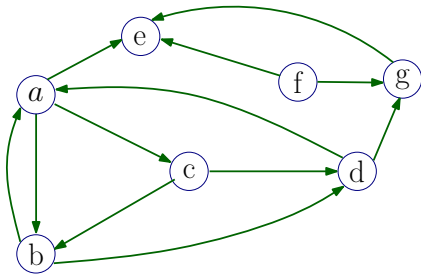
**ICP 14-31** What are diagonal entries of  $A$ ?

**ICP 14-32** How many 1's are there in row corresponding to vertex  $v$ ?

**ICP 14-33** How many 1's are there in column corresponding to  $v$ ?

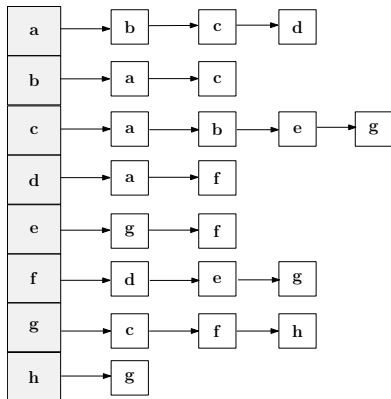
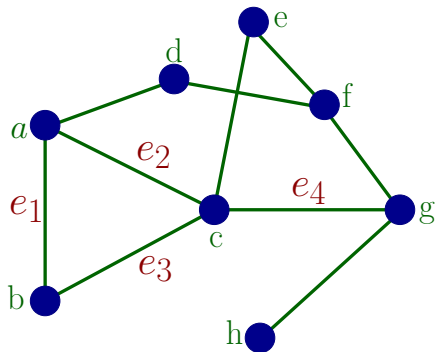
# Graph Representation: Adjacency List

Represent digraph by listing neighbors of each vertex



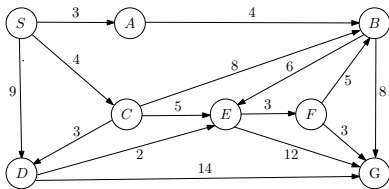
# Graph Representation: Adjacency List

Represent undirected graph by listing neighbors of each vertex





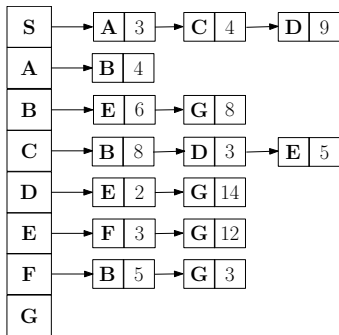
# Weighted Graph Representation



## Weighted Adjacency Matrix

	S	A	B	C	D	E	F	G
S	0	3	0	4	9	0	0	0
A	0	0	4	0	0	0	0	0
B	0	0	0	0	0	6	0	8
C	⋮							
D								
E								
F								
G								

## Weighted Adjacency Lists



# Graph Representation: Tradeoff

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$$G = (V, E), \quad |V| = n, \quad |E| = m$$

- Adjacency matrix representation
  - requires  $n^2$  bits
  - Edge query  $[(a, b) \in E?]$  requires one memory lookup
- Adjacency list representation
  - requires  $2m$  integers (vertex ids)  $\sim 2m \log n$  bits
  - Edge query  $[(a, b) \in E?]$  requires list traversal

Usually real-world graphs are very **sparse**  $m = C \cdot n \log n$

▷ So adjacency lists are preferred

For very **dense** graphs adjacency matrix is better

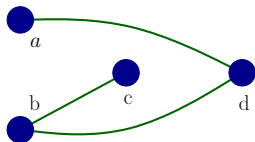
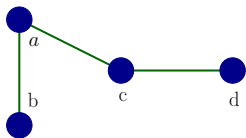
# Graph Complement

## Graph Complement

$$G = (V, E) \rightarrow \overline{G} = (V, \overline{E})$$

$$(u, v) \in \overline{E} \text{ iff } (u, v) \notin E$$

- Vertex set is the same
- Each edge become non-edge and each non-edge becomes edge  
▷ (except self-loops)



ICP 14-34

How to compute  $\overline{G}$  from adjacency matrix and list of  $G$  ?

# Graph Transpose

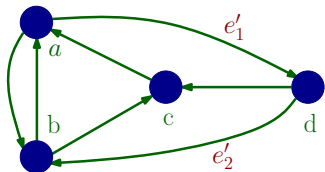
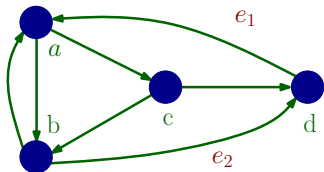
## Graph Transpose

$$G = (V, E) \rightarrow G^T = (V, E')$$

▷  $G$  is a digraph

$$(u, v) \in E' \text{ iff } (v, u) \in E$$

- Vertex set is the same
- Direction/orientation of edges are reversed



ICP 14-35

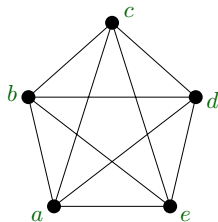
How to compute  $G^T$  from adjacency matrix and list of  $G$  ?

# Subgraph

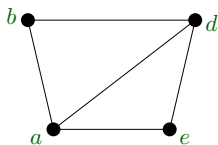
$H = (V', E')$  is a **subgraph** of  $G = (V, E)$ , if

$$V' \subseteq V \text{ AND } E' \subseteq E$$

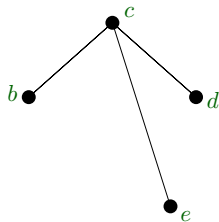
Denoted as  $H \subseteq G$



$G$



$H_1 \subseteq G$

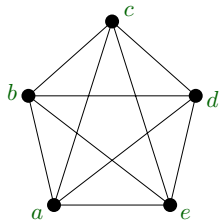


$H_2 \subseteq G$

# Induced Subgraph

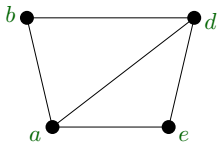
$H = (V', E')$  is a **induced subgraph** of  $G = (V, E)$ , if

$V' \subseteq V$  AND  $E' = E|_{V'}$  (all edges in  $E$  with both endpoints in  $V'$ )



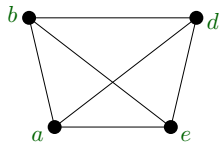
$G$

Not induced subgraph



$H_1 \subseteq G$

Induced subgraph



$H_2 \subseteq G$

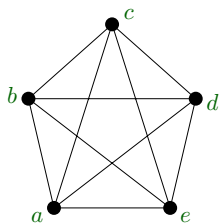
An induced subgraph is completely determined by  $V'$

# Spanning Subgraph

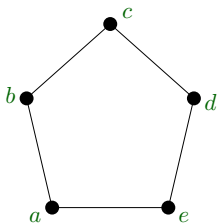
$H = (V', E')$  is a **spanning subgraph** of  $G = (V, E)$ , if

$$V' = V \quad \text{AND} \quad E' \subseteq E$$

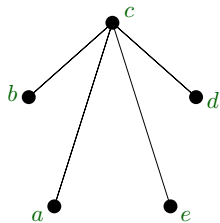
Denoted as  $H \subseteq G$



$G$



$H_1 \subseteq G$



$H_2 \subseteq G$