

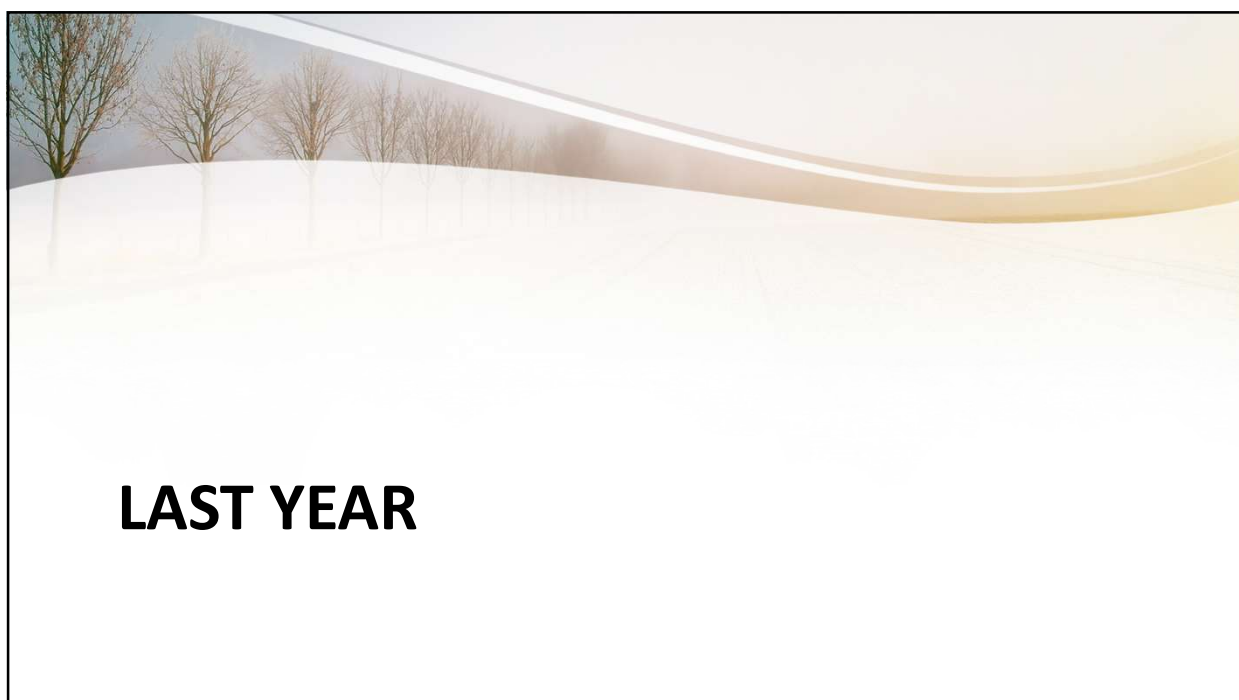


Towards Multipurpose Robotic End-Effector  
for Crop Husbandry

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**Mechatronics**  
MECHATRONICS & CONTROL ENGINEERING



**LAST YEAR**

## Robotic Pest Scouting & Crop Monitoring

**Concept:**

Robot working in the field, recording data and returning to base.







**Development:**

**The Robot:** 170x100 vehicle developed in AI & Robotics Lab

**The Sensor:** Soil moisture and pH, Local and remote sensing

**The Manipulator:** A commercial one arm manipulator (available in Lab)

**The Crop:** Cotton



**Currently!**

The sensor housing being upgraded

- 3D-Print
- 3D-Printed (Mechanism)
- Camera-based methodology



## Hybrid Drone for Crop Monitoring & Pesticide Spraying


**AI and Robotics Lab, UET Lahore**

**HYBRID INTELLIGENT MULTICOPTER**

Dr. Ali Fiaz  
Mr. Misbah ul Rehman

**Abstract**

The hybrid drone is designed to monitor the health of cotton plants and spray pesticides in case of any pest infestation. It is a hybrid drone with a camera and a pesticide sprayer. It is designed to monitor the health of cotton plants and spray pesticides in case of any pest infestation. It is a hybrid drone with a camera and a pesticide sprayer.



**Key Features:**

- 3D-Printed Chassis
- Flight Controller (ArduPilot)
- 3D-Printed Landing Gear
- 3D-Printed Motor Mounts
- 3D-Printed Pesticide Tank
- 3D-Printed Pesticide Nozzle

**Specifications**

- Weight: 2.5kg
- Flight Time: 20min
- Fuel Capacity: 8.5L
- Fuel Burn: 100ml/min
- Battery Type: 3S LiPo
- Operating Range: 1km
- Dimensions: 200 x 150 x 100mm


**Further Attachments:**

- GPS Module for Location Tracking
- 3D-Printed Motor Mounts
- 3D-Printed Pesticide Tank
- 3D-Printed Pesticide Nozzle

**Summary**

The hybrid drone is designed to monitor the health of cotton plants and spray pesticides in case of any pest infestation. It is a hybrid drone with a camera and a pesticide sprayer.






## Smart Agri-Sensor


**Concept:**

- A sensor
- collecting in-situ data
- communicating it to remote location
- to determine localized needs for:
  - irrigation
  - fertilizing



**Features:**

- pH Sensor
- Soil Moisture
- Air Humidity
- GSM Modules
- GPS Module
- RF Modules
- Local LCD Display
- Android App




## *Run-of-the-River* Turbine and Testbed

in collaboration with Petronas

Testbed was developed by our Lab  
Turbines were developed by supervised student groups

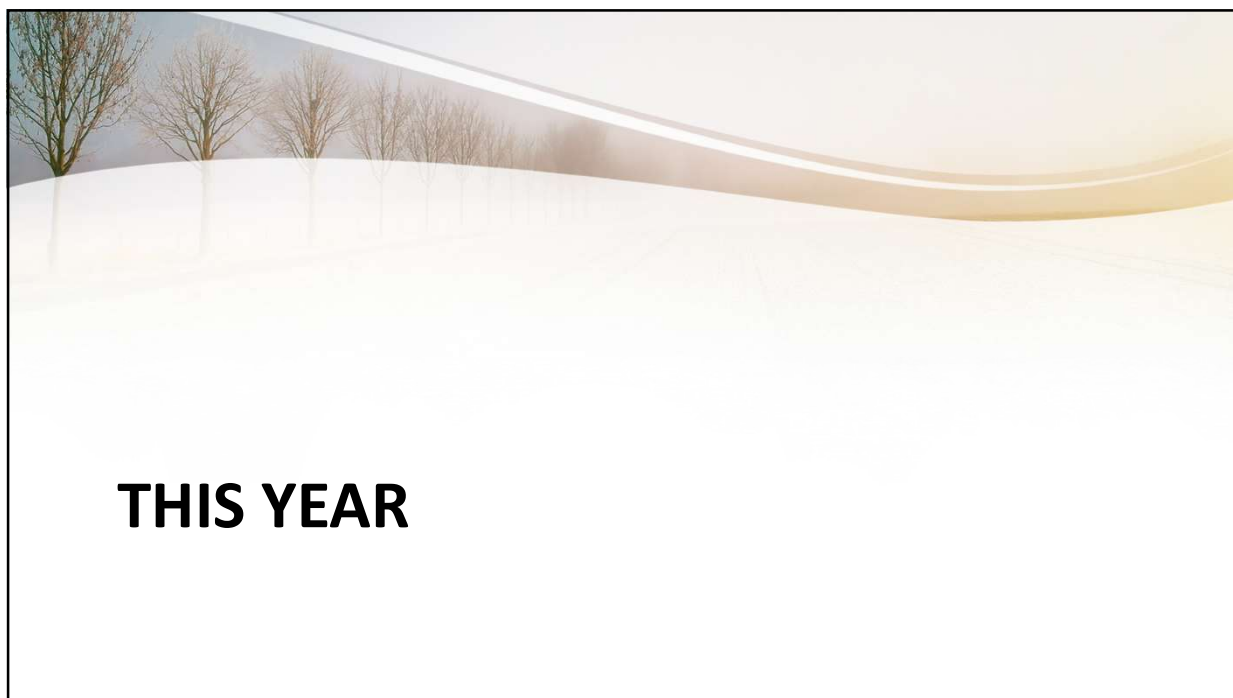
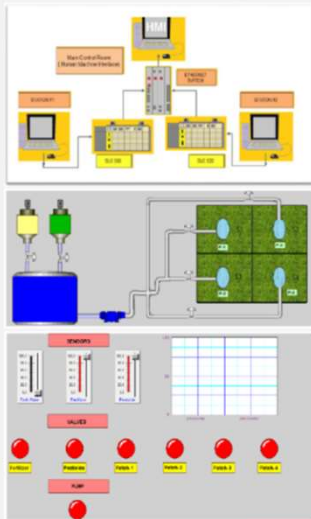



## Automation of Agri-Farms (PLC-based with HMI)

**Concept:**  
A system

- using Industrial Automation technology instead!
- to irrigate/fertilize large farms
- Reliable and Scalable
- with Human Machine Interface (HMI)

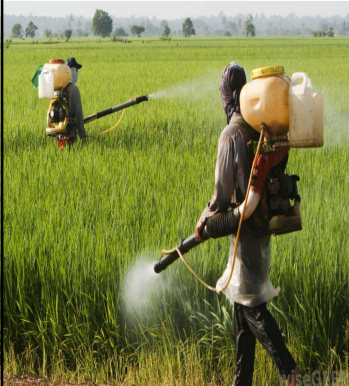






# Conventional Methods

- 1. Excessive use of Pesticides**
  - Adverse effects on health of soil & Environment
- 2. Excessive Tillage**
  - High Energy Consumption
  - Affects soil structure
- 3. Broadcasting the Seeds by Hand**
  - Labor intensive
  - High Seed Waste
  - Uneven Distribution
- 4. Excessive use of Water for Irrigation**
  - Waste of resources

# Conventional Methods

<b>Excessive Use of Pesticide</b>	<b>broadcasting the seeds by Hand</b>	<b>Conventional Irrigation</b>	<b>Tillage</b>
			

## CAN A MULTIPURPOSE TOOL BE DESIGNED?

Agri-Activity	Conventional/ Traditional Method	Proposed Method	Intended Benefits
Seedbed Preparation	1. Ploughing	Minimum tillage (agitation) through specially designed sowing tool	<ul style="list-style-type: none"> <li>• Energy conservation</li> <li>• Soil preservation</li> </ul>
Seeding	1. Throwing seeds 2. Manual Planters	The same tool having the seeding mechanism	<ul style="list-style-type: none"> <li>• Minimization of seed wastage</li> <li>• Precision in depth &amp; spacing</li> </ul>
Irrigation	1. Open Water Channels	Targeted irrigation through robotic movement and sowing tool	<ul style="list-style-type: none"> <li>• Greatly reducing the required water quantity</li> </ul>

Agri-Activity	Conventional/ Traditional Method	Proposed Method	Intended Benefits
<b>Fertilizer Distribution</b>	1. Throwing fertilizer 2. Mixing in Water Channels	Water soluble fertilizer distributed through the robotic end-effector	<ul style="list-style-type: none"> <li>Optimized use of fertilizer (saving the cost!)</li> </ul>
<b>Pesticiding</b>	1. Separate Pesticide Spraying	Integrated pesticide spraying	<ul style="list-style-type: none"> <li>Product and labor cost will be saved</li> </ul>
<b>Weeding</b>	1. Manual 2. Weeding Chemicals	Robotic agitation to weed out the unwanted plants	<ul style="list-style-type: none"> <li>Savings in cost of labor/ weeding chemicals</li> </ul>
<b>Soil Monitoring</b>	1. Manual operation	Automatically through Soil Sensor	<ul style="list-style-type: none"> <li>Optimal management of soil health.</li> </ul>

## Literature Review

- **Farm-Bot Genesis**
  - *Open source Blog*
- **Agricultural Robot for automatic ploughing and seeding**
  - *Ankita.A, Abirami.E, Amrita Sneha.A*
- **Autonomous Agricultural Robot towards robust autonomy**
  - *Martin Holm Pedersen & Jens Jense*
- **Valley Irrigation Pakistan**
  - *Farming Solution providers*

## ***Farm-bot Genesis (By Rory Anderson - California)***



## **Literature Review**

- **Iowa Agriculture literacy foundation**
  - *Agriculture Blog by WILL*
- **Soil Quality**
  - *Article by Dr Lengnick)*
- **Implementation of remote control for a spraying robot**
  - *by Chun-Mu Wu, Jui-Tsung Lu*
- **CROPWATCH-Institute of Agriculture and natural Resources**
  - *by University of Nebraska-Lincoln)*



## Objectives:

**To Develop a Multipurpose Robotic End-Effector that incorporates:**

- An Automatic digging mechanism
- An Automatic seed sowing mechanism
- A system that can irrigate or fertigate fields efficiently.
- A feedback system that can detect moisture level of the field.
- A system for weed detection and its effective removal.
- A system that can effectively spray pesticide.

- All packaged in one product
- Reconfigurable
- Versatile

## COMPARISON TABLE:

Products	<i>Farm-Bot Genesis</i>	<i>Maestro SW</i>	<i>Hand Seeder</i>	<i>C-P Irrigation System</i>	<i>Conventional Farming</i>	<i>Our tool mounted on C-P</i>
<i>Ability to serve in Big Fields</i>						
<i>Pest Control system</i>						
<i>Even seed Dispensing</i>						
<i>Automation</i>						
<i>Eco-Friendly</i>						
<i>Irrigation/ Fertigation</i>						

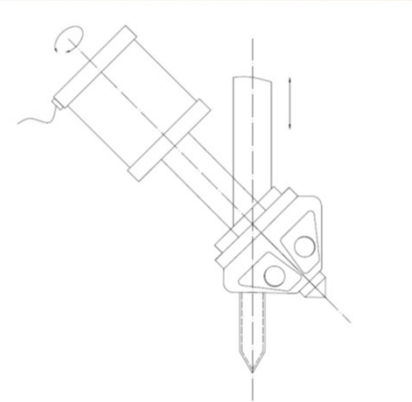
## Initial Design Multipurpose End-Effector

### *Multipurpose End-Effector*

Out of a number of initial options, an indexing tool design was considered to be the best option.

Selection Criterion:

- Expert Opinion
- Ranking on design objectives



## Applications & Scope

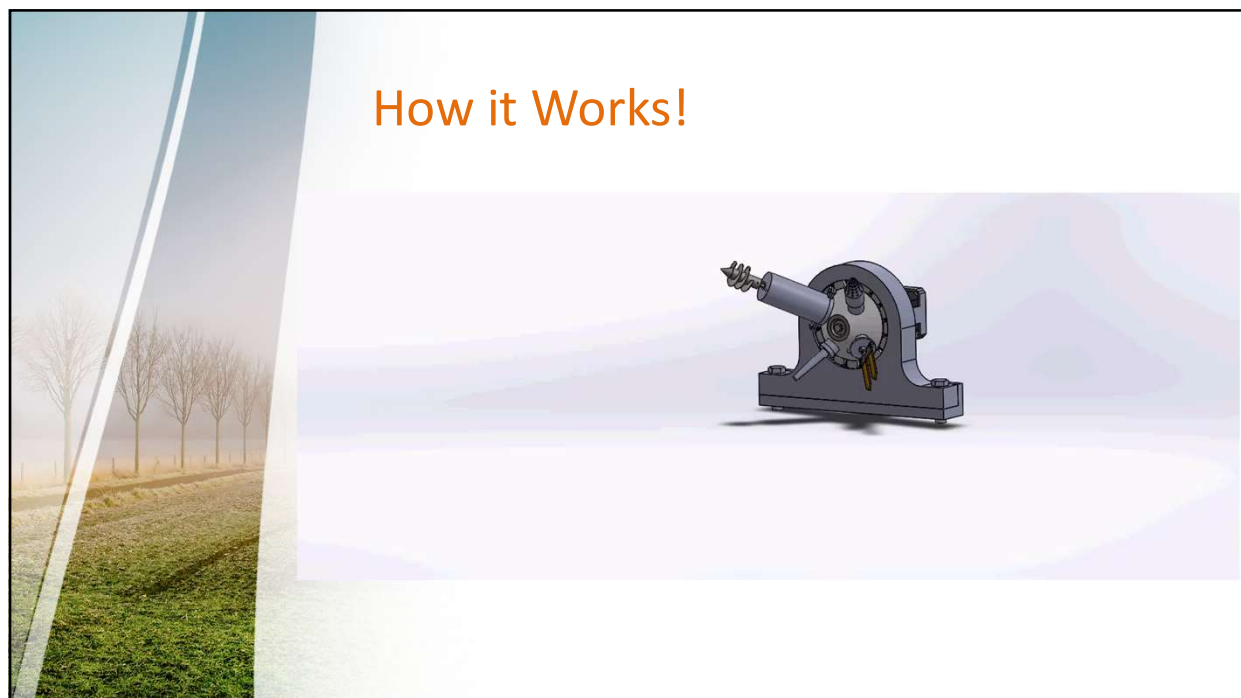
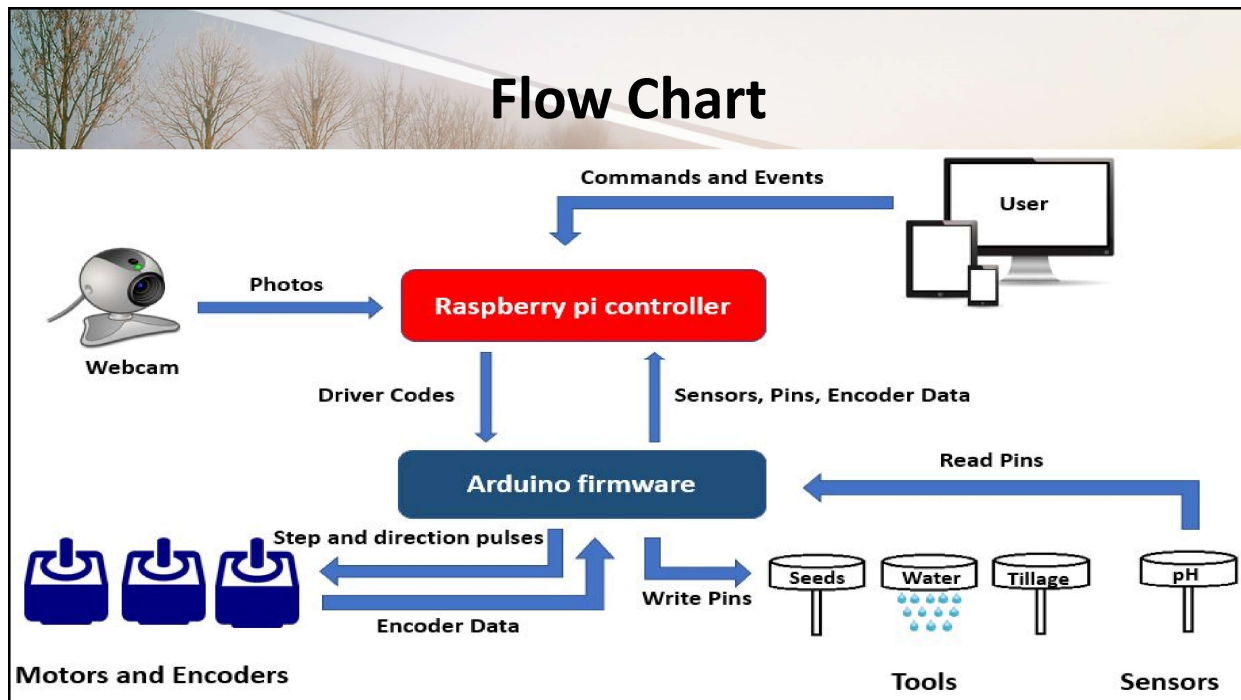
### **Applications:**

- Can be installed in any field ranging from medium to large for best performance and profit.
- Can be installed temporarily with the existing Central Pivot Irrigation system (rental services).
- Can perform Sowing , Tillage and Irrigation/Fertigation efficiently.

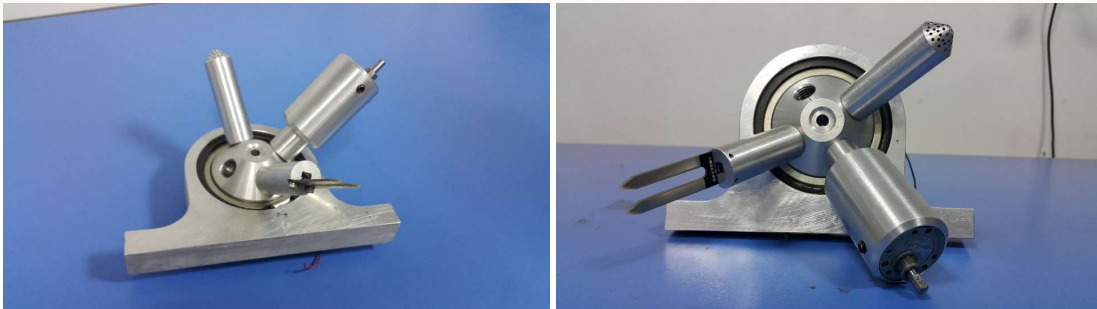
### **Scope:**

There is still a lot of room for improvement like:

- Can be made power efficient by equipping it with solar Panels.
- Can be used for Poly cultured and Mono Cultured Farms.
- Can benefit the economy if widely practiced.
- Can incorporate online data and cloud services.



## Final Assembly



- Two patents pending in Pakistan
- One US patent pending in USA



